

Single Remote Tower Technical Specifications Remotely Operated Tower Multiple Controlled Airports with Integrated Working Position

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Abstract

The objective of this document is to produce a technical specification that should work as a generic specification for Remote Tower for the future, not a specific implementation of a prototype. The Remote Tower is a new area without any earlier specifications and there is a need to write a specification foundation for the total concept.

This technical specification will be produced in four iterations:

- Iteration1 First draft of Single Remote Tower (this version)
- Iteration 2 Finalizing Single Remote Tower draft and first draft of the Multiple Remote Tower
- Iteration 3 Finalizing Multiple Remote Tower Draft
- Final iteration Finalizing all parts of the document



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103



104 **Executive summary**

- This document defines the Technical Requirements (functional and non functional) on a general levelfor Remote Tower.
- 107 This document will serve as a basis for the creation of a requirement specification for a specific implementation of a prototype.
- 109 Each prototype may implement only some or all of the capabilities
- 110 The Technical Specification will take in to account:
- 111 Remote Tower
- Virtual Tower

Experience and background regarding these concepts are partly based on previous NATMIG remote
 tower projects and SELEX real-time simulation and 3D representation projects.

- 115 Remote Tower is where ATS are remotely provided through the use of direct visual capture and visual 116 reproduction e.g. through the use of cameras. The ATS are provided using a Remote Tower Facility
- 117 (RTF), which includes the operator workstation(s), ATC systems and display screens.
- 118 Virtual Tower is where ATS are remotely provided through the use of computer generated images of
- the aerodrome, aircraft and vehicles, and/or surveillance e.g. through the use of terrain mapping and computer modelling of aerodromes.



121 **1 Introduction**

122 This document describes a generic set of system requirements for the Remote Tower concept.

123 It is assumed that the requirements mentioned in this specification are on a general level and for a 124 specific implementation of a prototype there is a need to produce a complimentary specific 125 requirements specification.

- 126
- 127

128 **1.1 Purpose of the document**

129 The relations between this technical specification and the other SESAR deliverables are illustrated in 130 *Figure 1.*



Edition: 00.00.02

147 **1.2 Intended readership**

- 148 The following potential audience have been identified:
- P12.01.07 (Airport System Specification drafting and Maintenance) is interested in the document to identify and maintain the consolidated list of requirements derived from each WP12 projects,
- P06.09.03 (Remote and Virtual Towers), which has produced related operational
 requirements

154 1.3 Inputs from other projects

- 155 The following input is used for requirements assessment:
- Project 06.09.03 (Remote and Virtual Towers) because it has provided the OSED document,
 which is the basis of this technical specification.
- Project 12.04.06 (Remotely Operated Tower Technology Enablers)

159 1.4 Structure of the document

- 160 This document is organized as follows:
- 161 Chapter 1: Purpose and scope; Requirements structure; Functional block purpose and high level 162 overview
- 163 Chapter 2: General functional blocks description
- 164 Chapter 3: Functional block Capabilities, Conditions and Constraints
- 165 Chapter 4: Assumptions
- 166 Chapter 5: Referenced documents

167 1.5 Requirements Definitions – General Guidance

- 168 The requirements in this document have been developed according to the SESAR Requirements and
- 169 V&V Guidelines (ref.[3]) and the SESAR Template Toolbox (ref.[4]).
- 170

171 1.6 Functional block Purpose

- The purpose of the development described in this specification is to provide a general specification forRemote Tower.
- 174
- Remote Tower
 - Virtual Tower
- 176 177
- 178
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- 185

186 **1.7 Functional block Overview**

187 The Functional block Model in this context is a high-level architectural representation of the Single

188 Remote Tower system design that is entirely independent of the eventual physical implementation.

- 189
- 190



195 196

Figure 3: Elements - Functional block model Single Remote Tower

"Italic text"

New element wirit current Control Tower

Interactions (including communication)

Equipment element

current Control Tower

Non-mandatory elements

Modified element w.r.t. current Control Tower

New data communication between sub elements w.r.t.

197

198 **1.7.1 Ground Elements**

199 Remote Tower System – ATC Unit

200 "Strategic-services" related elements:

Local Network Tools	Provides relevant information and tools for supporting the Supervisor's tasks as managing the airport restaffing resources.
Supervisor	Manages the airport/ATC unit resources/capacity in order to cope with the foreseen traffic (staffing, resectorisation, closure of the airport,)

201 "Pre-tactical/Tactical-services" related elements:

AI data system	Provides Aeronautical Information to the ATCo (AIP, NOTAMs, SNOWTAMs) to be used by supervisor and/or ATCo as necessary.
Flight plan system	Provides flight plan information to the ATCo for the aircraft flying/operating in the area of responsibility of the ATCo (TMA/Tower or Tower only) in form of paper strips or eventually electronic strips.
G-G COMM	Allows voice/data communication between ATCo and "other ATS unit ATCo". This supports the aeronautical fixed service AFS as defined in ICAO Doc4444 .
A-G COMM	Allows voice (VHF) / data (CPDLC) communication between ATCo and Flight Crew. This support the aeronautical mobile service as defined in ICAO Doc4444.
Surf-G COMM (vehicles)	Allows voice communication (VHF) between ATCo and vehicles drivers on the airport surface
Surf-G COMM (Airport personnel)	Allows voice/data communication between ATCo and airport personnel
Surveillance Data System	When available, it provides "real-time" surveillance data for the (equipped) aircraft flying/operating in a delimited (from x feet to FLxxx) area of responsibility of the ATCo.
Signalling Lamps System	Allows the ATCo to remotely manoeuvre the Signalling Lamps located in the airport premises.
Visualisation System	 Provides "real-time" images of the aerodrome*, the aerodrome traffic*, as well as any obstacle* in this area. A specific function allows a binocular view of particular element/objects. (*) as defined in ICAO Annex 11: <u>aerodrome</u>: A defined area on land or water (including any buildings, installations and equipment) intended to be used either wholly or in part for the arrival.



Visual Nav. aids System	 departure and surface movement of aircraft. <u>aerodrome traffic</u>: All traffic on the manoeuvring area of an aerodrome and all aircraft flying in the vicinity of an aerodrome. Note.— An aircraft is in the vicinity of an aerodrome when it is in, entering or leaving an aerodrome traffic circuit. <u>obstacle</u>: All fixed (whether temporary or permanent) and mobile objects, or parts thereof, that: a) are located on an area intended for the surface movement of aircraft; or b) extend above a defined surface intended to protect aircraft in flight; or c) stand outside those defined surfaces and that have been assessed as being a hazard to air navigation.
	"lighting" systems to support aircraft in "finding their way" to the airport, on the vicinity of the runway and on the airport surface (approach lighting, PAPI, threshold lights, airport beacon, runway and taxiway lighting, etc.)
Non-Visual Nav. Aids System	Allows the ATCo to remotely manoeuvre the different "non-lighting" systems to support aircraft in "finding their way" to the airport/runway (ILS, VOR, DME,)
Accident, incident and distress alarms	Allows the ATCo to monitor and trigger accident, incident and distress alarms as applicable to the aerodrome.
Airport Sound System	When available, it provides "real-time" noise from the airport (aircraft engines, wind sound,)
Local MET system	Provides to ATCo the relevant weather information on the airport (temperature, pressure/QNH, snow on the runway (?), wind direction/strength,).
CWP HMI	Allows to ATCo to get information from all previous systems and to interact with them as necessary
ATCo	Provides ATC services (described in section xx) by using the information provided in the CWP HMI. The related ATCo tasks are described in section xxx (based on the Task Analysis activity carried out in the frame of the HP assessment).

202 "Technical supervision" related elements:

Data Recorder	Allows to record operational data (ICAO requirement) including visualisation information.
Technical System status monitoring	Allows to monitor and detect any technical failure mode / degraded mode of the system
Voice Recorder	Allows to record voice communication on the applicable radio channels (ICAO requirement)
Technical personnel	In charge of the maintenance of the "Technical



supervision" elements

203

204 Airport Premises

Signalling Lamps System	Signalling Lamp is located in the airport premises, and remotely manoeuvred by ATCO from the remote ATC unit (RTC)
Visualisation System	Captures "real-time" images on the airport premises to be provided to the ATCo in the remote ATC unit (RTC)
Visual Nav. aids System	Visual Navigation aids are located in the airport premises, and remotely manoeuvred by ATCO from the remote ATC unit (RTC)
Non-Visual Nav. Aids System	Non-Visual Navigation aids are located in the airport premises, and remotely manoeuvred by ATCO from the remote ATC unit (RTC)
Ground Lights System	Ground Lights are located on the airport manoeuvring area, and remotely manoeuvred by ATCO from the remote ATC unit (RTC)
Airport Sound System	Captures "real-time" noise from the airport to be provided to the ATCo in the remote ATC unit (RTC)
Local MET system	Captures the relevant weather information on the airport to be provided to the ATCo in the remote ATC unit (RTC)

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206

207 **1.7.2 External Entities**

208 "Aircraft" elements:

Flight Crew	Pilots the aircraft using airborne information/systems and ATC instructions/clearances. They apply the corresponding rules and procedures as per ICAO Annex 2 and PANS OPS.
Aircraft (functions: SURV, COM, NAV,)	Encompasses all the onboard information/systems needed for the flight.
Aircraft (physical element)	The aircraft are captured by the Visualisation system in order to be remotely provided to ATCo

209

210 "Other ATC Unit" elements:

Other ATS Unit ATCo	ATCo coordinates with other ATS Unit ATCo for transferring departing/arriving aircraft, (with military) for activating / deactivating restricted areas,
Other ATS Unit System	Needed?



211 **"E-Network" elements:**

Regional NETWORK	Provides Regional flight plans for the day of
system	operations (CFMU) to local Network

212 "Airport premises" elements:

Driver	Drives the vehicle in the manoeuvring area as instructed by the ATCo
Vehicle (functions: COM,)	Encompasses all the information/systems needed for driving it and communicate with ATCo and other airport personnel
Vehicle (physical element)	The vehicles are captured by the Visualisation system in order to be remotely provided to ATCo
Airport Personnel	Management of the airport stands, pushback services, runway inspections,
Technical Personnel	Is in charge of the maintenance of the "remote" equipment located in the airport premises
Airport Surface	The airport surface is captured by the Visualisation system in order to be remotely provided to ATCo
Obstacles	Fixed (temporary or permanent) and mobile objects (including animals) that are captured by the Visualisation system in order to be remotely provided to ATCO
Airport Vicinity	Area close to the aerodrome (it includes aircraft which are in, entering or leaving an aerodrome traffic circuit) that is captured by the Visualisation system in order to be remotely provided to ATCo.

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215 **1.8 Acronyms and Terminology**

Term	Definition
ACC	Area Control Centre
ADD	Architecture Definition Document
ADS-B	Automatic Dependant Surveillance - Broadcast
AFIS	Aerodrome Flight Information Service
AFISO	Aerodrome Flight Information Service Officer
APOC	AirPort Operations Centre
APP	Approach
A-SMGCS	Advanced Surface Movement Guidance & Control System



Term	Definition
ART	Advanced Remote Tower Research Project
ATC	Air Traffic Control
ATCC	Air Traffic Control Centre
АТСО	Air Traffic COntroller
АТМ	Air Traffic Management
ATS	Air Traffic Service
CPDLC	Controller Pilot Data Link Communications
CWP	Controller Working Position
D-ATIS	Digital Automatic Terminal Information Service
DCL	Departure Clearance
DLIC	Data Link Initiation Capabilities
DOD	Detailed Operational Description
E-ATMS	European Air Traffic Management System
ICAO	International Civil Aviation Organization
ILS	Instrumental Landing System
INTEROP	Interoperability Requirements
IRS	Interface Requirements Specification
MLAT	Multi-Lateration
OSED	Operational Service and Environment Definition
отw	Outside The Window
ROT	Remotely Operated Tower (proof of concept project)
RTC	Remote Tower Centre
RTF	Remote Tower Facility
RVT	Remote and Virtual Tower Project
SESAR	Single European Sky ATM Research Programme
SESAR Programme	The programme which defines the Research and Development activities and Projects for the SJU.
SJU	SESAR Joint Undertaking (Agency of the European Commission)

Term	Definition
SJU Work Programme	The programme which addresses all activities of the SESAR Joint Undertaking Agency.
SMR	Surface Movement Radar
SPR	Safety and Performance Requirements
TAD	Technical Architecture Description
TS	Technical Specification
TWR	Aerodrome Control Service (which is a subset of ATC Service)
vcs	Voice Communication System

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218

219

220

founding members



221 **2 General Functional block Description**

222 **2.1 Context**

The SESAR Concept Storyboard defines three ATM Operational Steps (Step 1, Step 2, Step 3) which correspond to the original SESAR ATM Service Levels (Service Levels 2, 3 and 4 respectively). The Operational Steps tell the 'story' of what the SESAR ATM system will look like at key milestones in the implementation phase of 2010 to 2020.

227 P06.09.03 focuses on an *initial* concept for remotely provided ATS for single and multiple 228 aerodromes, for both ATC and AFIS as well as contingency operations.

The remote provision of ATS for a single aerodrome falls under SESAR Operational Step 1 (ATM Service Level 2). This operational service is already quite mature, having been developed initially in the ROT and ART projects. Whilst not yet delivering any 4D trajectory capability, the concept does provide optimised airport surface operations and a more efficient and cost effective deployment of operator resources. It is expected that the initial technical and operational capability of remote provision of ATS for a single aerodrome will be available from 2013.

The remote provision of ATS for a multiple aerodrome falls under SESAR Operational Step 3 (ATM Service Level 4). It is expected that the initial technical and operational capability of remote provision of ATS for a multiple aerodrome will be available from 2017 (see *Figure 4*).

The provision of ATS for contingency situations falls under SESAR Operational Step 2 (ATM Service Level 3). Whilst not yet delivering any 4D trajectory capability, the concept does provide optimised airport surface operations and a more efficient and cost effective deployment of operator resources. It is expected that the initial technical and operational capability of remote provision of ATS for contingency operations will be available from late 2016.





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The objective of Remote Provision for Aerodromes is to provide the air traffic services (ATS) defined in ICAO Documents 4444, 9426 and EUROCONTROL's Manual for AFIS for one or several aerodromes from a remote location i.e. not from a Control Tower local to the aerodrome. The full range of ATS should be offered in such a way that the airspace users are not negatively impacted (and possibly benefit) compared to local provision of ATS. The overall ATS will remain broadly classified into either of the two main service subsets of TWR or AFIS.

The Remote Provision of ATS for Aerodromes is expected to be applied mostly to low density aerodromes (where low density is determined as being mostly single simultaneous operations, rarely



exceeding two simultaneous movements). In the long-term the concept may also be applied for larger
 airports or small airports with occasionally more traffic density (for example touristic airports/remote
 airports during a particular event etc.)

258

The main change is that the ATCO or AFISO will no longer be located at the aerodrome. They will be re-located to Remote Tower facility or a RTC. It is likely that an RTC will contain several remote tower modules, similar to sector positions in an ACC/ATCC. Each tower module will be remotely connected to (at least) one airport and consist of one or several Controller Working Positions (CWP), dependent on the size of the connected airport. The ATCO will be able to perform all ATS tasks from this CWP.

265 2.2 Functional block Modes and States

266 2.2.1 Technical implementations

The Remote and Virtual Tower objective is to provide the air traffic services already provided by local aerodrome control Towers from a remote location.

This document is focused on the single remote TWR in its iteration one and two. This specification will be extended for a multi remote tower deployment in its iteration three and four. The main difference between Remote and a Virtual Tower is the technical solution used to implement the Outside The Window (OTW) vision service and related functions and services, as detailed in 2.2.1.1 and 2.2.1.2 paragraphs, while other ATS services could be more similar in both implementations.

- The distinction between remote and virtual tower can be found in P06.09.03 OSED chapter 1.6, (ref [8]), glossary of terms:
- 276
- In the **Remote Tower**, the OTW vision is remotely provided through the use of direct visual capture and visual reproduction through the use of cameras.
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- In the Virtual Tower the OTW vision is remotely provided through the use of computer generated images of the aerodrome, aircraft and vehicles, and through the use of terrain mapping and computer modelling to represent aerodromes. The virtual tower requires that the remote airport has radars, ground sensors and/or an A-SMGCS system to provide the Virtual Tower with data (system tracks) describing type and kinematics of all mobiles in the aerodrome.
- 286
 287 Both Remote and Virtual Tower share the concept that ATS services are provided using a **Remote**288 **Tower Facility** (RTF), which includes the operator workstation(s), ATC systems and display screens.
 289 The building where one or more RTF are housed is defined as **Remote Tower Centre** (RTC).

290
 291 Most of ATS function/services implemented by the Integrated CWP are the same for both
 292 Remote/Virtual Tower:

- Radio communications between ATCO/AFISO in RTF and flight crews.
- Radio communications between ATCO/AFISO in RTF and remotely controlled tower/airport.
- Phone communications between ATCO/AFISO in RTF and remotely controlled tower/airport.
- Presentation of surveillance data.
- ATC and voice data recording.

Local control systems at the airport (such as ground lights and navigational aids) adapted for remote
 control.



Radar, A-SMGCS and surveillance data and weather information will be gathered and displayed at
 the Remote Tower Centre. Technical implementation of these functions may vary, but generally it
 does not depend on type of the tower (Remote/Virtual). The multi sensor surveillance data, optional in
 the Remote the Remote Tower, are among the main requirements for the Virtual Tower.

307 **2.2.1.1 Remote tower**

The Remote Tower includes controller working positions for remote airport control. They incorporate all necessary control systems, live video presentation and additional remote tower specific systems.

310

The OTW vision in Remote Tower is based on live video image captured at the remote airport and sent to the remote tower centre. The live video image will provide the ATCO/AFISO with an out-thewindow view similar to an actual ATS tower.

314

A set of fixed cameras on the dismissed local tower (or other airport structure/building) in the remotely controlled airport send to the RTC live images of the airport and it surrounding as viewed by a local ATCO/AFISO. Each camera could be a multi spectral camera (B&W/RGB/IR) or a set of dedicated single spectral cameras to enhance the vision in cases of low visibility operations. A secondary set of cameras could provide an alternative point of view.

One or more remotely controlled (by ATCO/AFISO) electro-optical system implements the "binocular"
 function to have more detailed vision.

A multi display system or a circular video wall reproduces the OTW vision of the remotely controlled
 aerodrome.
 aerodrome.

327 Ground radar, ground sensors data, A-SMGCS data received from remote controlled airport are 328 presented on the CWP display.

The ATCO could select a subset of data presented on CWP and display them on a graphic overlay on
 OTW representation implementing a head up display function.

- Data recording function will provide video and voice communication recording and playback.
- Sounds and noises of remotely controlled airport are delivered in RTC
- 335

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336 **2.2.1.2 Virtual tower**

The Virtual Tower includes controller working positions for remote airport control. They incorporate all
 necessary control systems, OTW vision is remotely provided through the use of computer generated
 images of the aerodrome, aircraft and vehicles, and additional remote tower specific systems.

The OTW vision in Virtual Tower is remotely provided through the use of computer generated images of the aerodrome, aircraft and vehicles. The 3D model of the remote aerodrome is generated through the use of terrain mapping and computer modelling. System tracks gathered from remote airport are represented in a 3D real time animation on the digital 3D model of remote airport. The digital animation will provide the ATCO with a virtual out-the-window view.

System tracks are multi sensor tracks received by Virtual Tower as A-SMGCS real time messages.
 The track fusion of radars tracks and other surveillance sensors of remotely controlled airport
 generate the A-SMGCS system tracks.

Radar and A-SMGCS system tracks received from remote controlled airport shall presented on CWP
 display.
 display.

A dedicated software gateway real time translates A-SMGCS system tracks in DIS/HLA entities, used as input of the 3D model/display system. A mobiles database contains a complete set of known aircraft, ground mobiles as truck, buses and cars. Tracks matching with database entities are visualized with their attributes (e.g. aircraft model with proper airline skin) Tracks without a match inside the database will display as intruders or obstructions depending on their kinematics.



- Time of day, data about daylight/night/dawn/dusk and meteo in remote controlled aerodrome generate the environmental data for 3D airport model, enabling the simulation of day and night, sun position, rain or fog. ATCO could switch on/off the visualization of environmental data in 3D representation.
- A multi display system or circular video wall emulates the OTW vision of the remotely controlled
 airport.
- The ATCO could select an entity on CWP display, the corresponding entity on the virtual OTW is highlighted and a graphic overlay will display a subset of the entity data.
- Data recording function will provide system tracks recording and playback.
- Radio communication recording function to record/reply radio.
- Sounds and noises of remotely controlled airport are delivered in RTC
- 371

357

372 2.2.2 Operating modes

373 2.2.2.1 Remote provision of air traffic services to a single aerodrome

- 374 Not in the scope of this first iteration
- 375 2.2.2.1.1 Shared operation with single aerodrome
- 376 Not in the scope of this first iteration

377 2.2.2.2 Remote provision of air traffic services to multiple aerodromes

Remote provision of air traffic services to multiple aerodromes are not within the scope of iteration
 one of this specifications. Technical specifications for a solution covering the provision of air traffic
 services on multiple aerodromes will be produced by iteration 3 and 4 of this document.

381 **2.2.2.3 Contingency operations**

Contingency operations are not within the scope of these specifications. Technical specifications for a solution covering contingency operations will be produced by P12.04.08 *Remote Tower Technologies* used for contingency and enhanced local operations.

- 385 **2.2.3 Operational environments**
- 386 2.2.3.1 ATC
- 387 Not in the scope of this first iteration
- 388 2.2.3.2 AFIS
- 389 Not in the scope of this first iteration

390 391

- 392
- 393
- 394



2.3 Major Functional block Capabilities

396 **2.3.1 Context**

The approach for the major functional block decomposition and capabilities for remote tower systems is based on enhancements over component structure of a standard tower (as defined in project B4.3). It should cover all the main functional parts which need to be addressed for a standard tower as well as the enhancements and extensions needed for a remote tower. Dedicated components might be enhanced with additional functionality required to support the remote tower operation scenario.

This chapter will provide an overview of all functional blocks as defined by B4.3 and highlight the remote tower specific capabilities and extension. A further component breakdown will be done in 2.6 chapter.

This description is focused on the single remote TWR scenario. This description will be extended in the future for a multi remote tower deployment and for contingency situation scenarios.

407 **2.3.2 Design decisions**

According to the profiles defined in the operation concept description DEL-06.09.03-D02-OSED some of the component might not be of use for airports categorized for remote tower usages in terms of movements and capacity.

- 444 This diagram based on D42 decomposition shows the
- 411 This diagram, based on B4.3 decomposition, shows the functional blocks which should be taken into account and those ones to be taken into account (at least for initial phases of the remote tower).



413 414

415

Figure 5: Functional Components for TWR as defined in B4.3

- 416 This design decision leads the project to focus on the design of definition of the next functional blocks:
- 417 Extended Aerodrome Surveillance for remote TWR
- 418 Extended Ground Correlation Management for remote TWR
- 419 Aerodrome Flight Data Processing
- 420 Aerodrome Conflict Management
- 421 Extended Support Functions for remote TWR
- 422 Ground Lighting Management
- 423 Extended Controller Human Machine Interaction Management for remote TWR
- 424 Extended Operational Supervision for remote TWR
- 425 Extended Technical Supervision for remote TWR



- 426 Extended G-G Voice Communications for remote TWR
- 427 Extended A-G Voice Communications for remote TWR
- Extended Visualization using multispectral cameras in Remote video based Tower.
- 429 Extended visualization using synthetic 3D representation in Virtual Tower,

430 2.3.3 Major functional block capabilities diagram

431 The following diagram describes the external functional blocks connected with the remote provision of 432 air traffic services to a single aerodrome and it's internal functional blocks.

433



434 435 * Not part of the Aerodrome ATC System Architecture

Figure 6: Functional blocks and their interactions

The requirements defined in this document are grouped for services (please refer to [8]) in order to meet the approach followed by Operational requirements.

This diagram is focused on the single remote TWR scenario. This diagram will be extended in the future for a multi remote tower deployment and for contingency situation scenarios.

440 **2.4 User Characteristics**

441 **2.4.1 ATCO/AFISO**

442 The ATCO/AFISO will have main responsibility for the provision of ATS.

443 The TWR ATCO is responsible for assuring safe operations and provision of air traffic control services

for the aerodrome manoeuvring area and the vicinity of the aerodrome. This includes responsibility

- for clearance delivery, ground control, arrival management, departure management and flight data
- 446 processing. The AFISO is responsible for the provision of the AFIS.



447 **2.4.2 Watch supervisor**

The (optional) Watch Supervisor could have main responsibility for staff/CWP allocation in an RTC with several workstations connected to several airports.

450 During a shift, a Watch Supervisor role can be used to manage the allocation of staff and CWP at any 451 one time during the shift in order to provide an efficient set up at all times and guarantee a flexible 452 system. The Supervisor role can be performed by a dedicated person, or can be handled by one of 453 the shift staff in addition to their ATCO/AFISO role.

- In order to maintain the overall traffic picture required for the staff/CWP allocation, the Supervisor may either:
- Be a separate and <u>extra role</u> with overall responsibility for the management of the RTC. The Supervisor maintains overall vision of all aerodromes within the RTC at all times in addition to the ATCO/AFISO providing ATS. This role could be performed from a dedicated Supervisor CWP. The Supervisor would be expected to perform the planning, administration, staff management and staff allocation tasks, and supervision of technical systems, allowing the ATCO/AFISO to concentrate solely on the provision of ATS. Since this is an "extra" role, it is expected that this type of role would only be required for the larger or more complex RTC;
- •Perform the role in combination with the duties of a regular ATCO/AFISO, and therefore not be a
 separate role.
- 465

466 **2.4.3 Airspace user**

The airspace users (through the pilots but also for example vehicle drivers on the airport manoeuvring
 area) are receivers of the ATS service. However, as previously stated, neither their role nor their
 responsibility should change as a result of introducing the remote aerodrome ATS.

470

471 **2.4.4 Technician**

Technicians will monitor the status of systems and perform maintenance as appropriate, both on the remote facility site and the airport side and related systems.

474

475 **2.4.5 Other stakeholders**

- 476 Other stakeholders might be:
- Airport Rescue Units; could utilize by external sharing of the visual reproduction for quick
 response and localization of the emergency, even during low visibility and without being
 dependent on information passed on by ATCO personnel.
- Airfield security and ground handling; could be alerted of unauthorized infringements on the manoeuvring area, debris on the runway and other safety and/or security related issues.
- 482
 •AirPort Operations Centre (APOC); could utilize the visual reproduction for situation assessment and short term planning.
- •Ordinary control tower personnel; could benefit from increased situational awareness by the introduction of parts of the RVT technology into ordinary control towers.
- 486 •Local airport officers
- 487

488 **2.5 Operational Scenarios**

489 The operational scenarios are described in the OSED chapter 5. (ref [8])



490 2.6 Functional

491 **2.6.1 Functional decomposition**

The functional breakdown is focused on the single remote TWR scenario. In a multi remote tower deployment certain capability will be extended.

The functional decomposition of the remote tower system is based on the component structure defined for the standard tower (project B4.3 ref [7]). Some of the components will not be of use for airports categorized for remote tower usages in terms of movements and capacity (as defined in the operation concept DEL-06.09.03-D02-OSED ref.[8]). Specific components might be enhanced with additional functionality required to support the remote tower operational scenario.

This chapter will provide an overview of all functional components as defined by B4.3 and highlight the remote tower specific capabilities and extension. A further component breakdown is done on functional blocks dedicated to remote tower enhancements (e.g. Surveillance / Visualization and HMI)

502 The main building blocks are independent of a specific implementation of a remote tower solutions 503 (video based or virtual tower). If components are only applicable for one solution approach this is 504 clearly indicated.

- All components marked in red are considered as relevant for remote tower solutions.
- 506



507

508

Figure 7: Functional Component for TWR as defined in B4.3 (ref [7])

509

510

511 2.6.1.1 Aerodrome Surveillance

512 This functional block provides controllers with airport situational awareness on the SID(s), STAR(s), 513 apron(s), taxiway(s), runway(s) and landing/take-off paths by providing position and identification of all 514 surface traffic (aircraft and vehicles). It merges the surveillance information provided by the different 515 surveillance sources providing a unique picture of the actual traffic situation. For each aircraft, vehicle 516 and obstacle a system track is generated.

517 In context of remote tower mainly the Airport Surface Surveillance Infrastructure will be adapted.

518 There will be no remote tower specific enhancements for the EnRoute TA Ground SUR Infrastructure.

519



520

Figure 8: Surveillance Infrastructure as define in B4.3 (ref [7])

522

521

523

524 The aerodrome surveillance component will be extended in a remote TWR system by introducing a 525 dedicated function to gather data for visualization to replace the classical out of the window view of 526 traditional towers. Visualization and surveillance capabilities will be combined to enhance situation 527 awareness for the remote control scenario. Specific issues such special weather conditions, different 528 sun light conditions and replacement of binocular view have to be addressed by this component.

529

530 Standard surveillance sensors such as SMR or MLAT might not be applicable for remote towers in a 531 first step and will be considered for virtual remote towers.

- 532 In addition new components are introduced for the video based remote tower approach:
- 533 Video stream management
- 534 Camera Control
- 535 Visual Tracking
- 536 Video Data Fusion
- 537



539

Figure 9: Functional decomposition of Surveillance / Visualization for video based remote twr

540

541 Video Stream Management:

542 This component includes handling of video data from several local cameras and transferring this data 543 to the remote tower centre. It includes bandwidth management and compression, monitoring of delay

544 times, frame rate and access control.

545 Camera Control:



- 546 The component provides access to control functions of cameras. This functional block includes 547 authentication functions and control function related to image adjustments/optimization and PTZ 548 control.
- 549 Visual Tracking:
- 550 This component performs automatic object tracking functions based on the managed video streams.
- 551 Output of this component is position information of the identified object or marking of the identified 552 object in the video stream.
- 553 Video Data Fusion:
- 554 Data fusion combines different inputs from surveillance sensors and generates a aggregated system 555 track for a dedicated object.
- 556 Future additions for other low cost surveillance technologies shall be considered.

557 2.6.1.2 Ground Correlation Manager

- 558 This functional block has the responsibility of logically associating surveillance data with an aircraft or 559 vehicle. This association is called ground correlation.
- 560 In context of remote tower this function might be used in a limited way dependant on the available 561 surveillance capabilities.

562 2.6.1.3 Aerodrome Flight Data Processing

563 This functional block manages the creation, update and modification of system flight plans up to/from 564 the moment the aircraft takes-off/lands. In addition, it calculates the predicted trajectory by taking into 565 account applicable constraints and relevant data (e.g. aircraft performance, weather data, airport 566 configuration data, wake vortex characteristics associated to each aircraft). Aerodrome Flight Plan 567 should be updated at the occurrence of identified significant events such as, for example: request and 568 approval clearance for Start-Up, Push Back, Taxi, Line-Up, Take-Off and similarly for landing aircraft.

569 In context of single remote tower this function is used as defined for the standard tower.

570 2.6.1.4 Aerodrome Conflict Management

571 This functional block detects within manoeuvring areas (runway/s and taxiways) potential conflicts 572 between two objects (i.e. aircraft or vehicles), or between an object and a restricted area, by 573 processing the actual traffic situation, It is also extended to final approach and take-off paths. The 574 potential safety hazards situations on the airport movement area encompass: runway incursion,

575 intrusion in protected areas, aircraft/aircraft and aircraft/vehicle collisions.

576 In context of remote tower this function will be limited due to restricted capabilities provided by the 577 aerodrome surveillance functions.

578 2.6.1.5 Support Functions

- 579 The Support functions do not affect directly the provision of ATM Services at operational time. They 580 contain at least the following:
- 581 Recording performing the recording of the ATM System data related to the Aerodrome 582 ATC, and buffering those data on a persistent database.
- 583 Playback providing support for display and voice recording, display and voice playback, 584 other data recording and reduction, etc.
- 585 Data analysis providing support for maintenance, investigation etc.
- 586 Automatic Safety Data Gathering Tool providing support for safety aspects.
- 587

588 In context of a video based remote tower supporting functions will be extended by recording of video 589 streams and additional audio feed (from the airport environment).



590 2.6.1.6 Ground Lighting Management

This function provides the functionalities, for the Aerodrome ATC users, to control and monitoring in 591 592 real time that the entire "light system" is constantly able to support the operative needs, in order to 593 assure all the airport operations in an appropriate way under all conditions (e.g. CAT I, CAT II, CAT III). This system is also the main enabler to support and implement the Surface Guidance. 594

595

596 In context of remote tower this component will be used in a limited way. Focus is the standard control 597 and status feedback of all airfield light segments via the remote tower centre. Surface Guidance 598 functions are not in scope for this category of airports.

599

2.6.1.7 Controller Human Machine Interaction Management 600

601 This functional block provides controllers with a graphical user interface and with the means to 602 interact with the Aerodrome ATC system. 603

604 The Controller Human Machine interface will be extended by visual representation to replace the 605 traditional out of the window view and other capabilities such as acoustic information. 606

- 607 A further functional breakdown will lead to:
 - **OTW** Visualization
- 610 Standard Functions (Communication, Information & Control, Flight Data Display, 611 Surveillance Display)
 - Airport Sound
- 612 613

608 609

- 614
- 615
- 616



618 619

Figure 10: Functional decomposition of Remote TWR Controller Working Position

- 620 A further functional breakdown will lead to: 621
- 622 Visualization Optimizations/ Display
- Augmented Reality 623
- 624 Camera Selection / Interaction _
- 625 Virtual 3D airport model and ground traffic display
- Standard Functions (Communication, Information & Control, Flight Data Display, 626 _ 627 Surveillance Display)
- 628 Airport Sound
- 629
- 630
- 631

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633 634

632

635 OTW Visualization:

This component will depend on the selected implementation approach for the remote tower. For a
 video based solution visualization will cover layout and display of multiple camera streams, selection
 and interaction of specific camera views and overlay of additional support information in the video

639 display.

640 In case of a virtual tower solution this component will handle rendering of a virtual display for the 641 tower view, selection of view points and embedding of objects and other information in the virtual 642 view.

642 643

644 Airport Sound:

This component provides real time environment sound from the airport to increase situation

- 646 awareness for the controller.
- 647

648 Standard Functions:

- 649 This block is covering HMI of all systems used in traditional towers.
- 650
- 651

652 **2.6.1.8 Operational Supervision**

This functional block allows the Supervisor to manage the most appropriate operational configuration,
 according to traffic demand and aerodrome needs, and to react in case of system fault, re-assigning
 and distributing available resources in order to maintain adequate safety levels and quality of service.

656 In context of the single remote tower this function is hosted in the remote tower centre and will be 657 equivalent to the standard tower (may be extended for the multi tower scenario).

658 2.6.1.9 Technical Supervision

- This functional block is in charge of the technical supervision of an Aerodrome ATC system (e.g. monitoring the services provided by the system, starting, stopping or re-starting the system or part of it).
- 662 The Technical Supervision encompasses the following functions:
- Presenting technical and functional systems status: monitor system availability.
 Acquire, synthesize and display technical and functional status on all the system
 hardware/software resources.
- Providing failure detection and analysis assistance: generate alarm or warning on failure detection. Provide support for analysis of supervision data (enable queries on historic of events).
- 669 Providing supervision commands and actions: accept supervision commands/actions (e.g. (Re)start/stop/stand-by/reset/switch-over) from eligible operators and gives the capability to perform maintenance activities.

In context of the remote tower the technical supervision is deployed in a distributed environment andhas to cover equipment hosted at the airport and the remote tower centre.



674 **2.6.1.10 Aerodrome Voice**

The Aerodrome Voice Domain system provides Voice front-end functionalities (Telephone and Radio
 Voice Communication Switching functionalities, typically).

677 Air-Ground Voice Communications:

678 This functional block provides the functions performed by a Radio VCS

679 In the remote tower operation scenario the air ground communication is not directly interconnected to 680 the local radio. The remote located remote tower center needs a dedicated connection to the local 681 radio to access air ground communication. Therefore additional infrastructure and an access gateway

682 for the radio will be required.

683 Especially for a backup or emergency radio system a dedicated backup connection between the local 684 tower and the remote tower center will be required. Standard fall back solution such as handheld

radios used directly in the tower is not applicable for the remote tower scenario.

686

687

688 Ground-Ground Voice Communications:

689 This functional block provides the functions performed by a Telephone VCS.

690

691 Remote Tower specific enhancements for this component are related to management of remote and 692 an optional local VCS position for backup or transition purpose.

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- 700
- 701



703 2.6.1.11 Network Infrastructure



729 **2.6.2 Functional analysis**

730



731 732

Figure 12: Functional relation

733

The figure above lists all functional components of the remote tower solutions and their dependencies and relations. Furthermore external systems or sensors which are related to the remote tower systems are shown. The logical information flow of flight data, support information and voice communication is the same as for the standard tower. Main difference is the remote connection to dedicated information sources at the local airport and the acquisition of this information via the WAN infrastructure.

The central element is the Controller HMI, which combines functions from the other components to an integrated controller working position. A remote tower specific part of the HMI is the OTW Visualization component. It uses mainly the Airport Surveillance functions to replicate the out of the window view. In case of the video based remote tower implementation the visualization is based on the video surveillance component which is attached to local camera sensors.

The Airport Surveillance and Video Surveillance block is processing sensor data (radar data / video streams) from the local airport, which are transferred via the network infrastructure. Parts of the processing may be performed locally at the airport or at the RTC. The exact deployment is a matter of detailed design and specific for a dedicated implementation.

749 Other data such as support information or status and control of airfield light are also integrated in the 750 controller working position. Selected support information might be directly embedded into the 751 visualization component (e.g. as overlay information). A similar process is applied for events 752 generated by the Aerodrome Conflict Management, which will be shown in the controller HMI as 753 warning or alert.

The information flow for technical supervision starts at the acquisition of status information of all technical equipment at the local airport or in the remote tower center. Status information is aggregated and processed for presentation.



757 Voice Communication is interconnecting local radios and standard phone interfaces. All data are 758 transferred via the common network infrastructure. Voice Communication functions are integrated in 759 the controller HMI.

760

2.7 Service View 761

- 762 As no 12.1.7 TAD is available at this stage of the project, this service view is not applicable for step1.
- 763
- 764



765 3 Functional block Functional and non-Functional 766 Requirements

767 **3.1 General functional requirements**

768 3.1.1.1 Communications services

769

Identifier	REQ-12.04.07-TS-0100.0001		
Requirement	The RVT shall provide the ATCO/AFISO with access to aeronautical mobile service (air-ground communications) in the area of responsibility.		
	Air-ground communications		
	PEO-06.09.03-05ED-0002.1001		

REQ-06.0 <SATISFIES> <Enabler>

773

771 772

Identifier	REQ-12.04.07-TS-0100.0002					
Requirement	The RVT <i>shall</i> provide the ATCO/AFISO with access to aeronautical fixed					
	service (ground-ground cor	service (ground-ground communications, in accordance with ICAO Annex 11,				
	Chapter 6.2) in the area of responsibility.					
	Ground-ground communications					
REQ-06.09.03-OSED-0002.1002						
<satisfies></satisfies>	<enabler></enabler>					

777

775

Identifier	PEO 12 04 07 TS 0100 0002
Identillei	REQ-12.04.07-13-0100.0003
Requirement	The RVT shall provide the ATCO/AFISO with access to surface movement control service (communications for the control of vehicles other than aircraft on manoeuvring areas at controlled aerodromes) for the aerodrome and its vicinity.
	Ground-ground vehicle communications

REQ-06.09.03-OSED-0002.1003 <SATISFIES> <Enabler>

781

779

Identifier	REQ-12.04.07-TS-0100.0004
Requirement	The RVT <i>shall</i> provide the ATCO/AFISO with signalling lamp functionality (characteristics according to ICAO Annex 14 section 5.1.3).
	Note: The means of directing the signalling lamp towards the applicable aircraft may be combined with the binocular function, see RVT-VIS-30a/b/c/d (REQ-06.09.03-OSED-0003.0035 to 38).
	Signalling lamp functionality
	orginaling lamp functionality

REQ-06.09.03-OSED-0002.1004

785

783

Identifier	REQ-12.04.07-TS-0100.0005
Requirement	 If meteorological conditions permit, the RVT <i>shall</i> enable the ATCO/AFISO to observe visual communication from aircraft that are within visual range, such as: aircraft flashing landing lights or flashing navigation (in darkness) aircraft repeatedly changing its bank angle – "rocking wings" (in daylight)
	 such as: aircraft flashing landing lights or flashing navigation (in darkness) aircraft repeatedly changing its bank angle – "rocking wings" (in daylight)

	Visual communication from aircraft		
787			
	REQ-06.09.03-OSED-0002.1005		
789			

Identifier	REQ-12.04.07-TS-0100.0006
Requirement	If meteorological conditions permit, the RVT <i>shall</i> enable observation of visual communication from aircraft that are within visual range on the aerodrome manoeuvring area, such as: • moving ailerons (or rudder). (in daylight) • flashing landing lights (in darkness)
	Visual communication from aircraft on manoeuvring area

Identifier	REQ-12.04.07-TS-0100.0007	
Requirement	If the RVT is "Virtual Tower" it shall receive surveillance data from the controlled aerodrome to feed with live traffic the virtual 3D airport visualization	
	Surveillance data from remote controlled airport.	

798 3.1.1.2 Voice Communication

799 [REQ]

[=~]			
Identifier	REQ-12.04.07-TS-0100.0008		
Requirement	The voice distribution <i>shall</i> be compliant with EUROCAE Working Group 67		
	recommendations if it is an IP-solution.		
Title	Voice Communications Network Performance		
Status			
Rationale			
Category	<performance></performance>		
Validation Method			
Verification Method			

1 [REQ Trace]

[REQ]	
Identifier	REQ-12.04.07-TS-0100.0009
Requirement	The system <i>shall</i> support a hierarchical side tone generation configuration.
Title	Hierarchical Side Tone Generation
Status	
Rationale	Local side tones improve audio quality since the round trip time from the CWP to the radio has no influence. Especially in the remote TWR setting network delays may occur, which shall not influence the audio experience of the controller.
Category	<functional></functional>
Validation Method	
Verification Method	

[REQ Trace]

	REQ-06.09.03-OSED-0002.0001				
	A-G Voice Communications				

807	IREQ1							
001	Identifier	REQ-12.04.07-TS-0100.0010						
	Requirement	The system shall support shared access to the radio infrastructure.						
	Title	Shared Radio Access						
	Status	Status						
	Rationale	Radios exits.	s have to be accessed	d in parallel by a local and remo	te CWP if such			
	Category <functional></functional>							
	Validation Method							
	Verification Method							
808								
809	[REQ Trace]							
810								
810								
813	[REQ]							
814	Identifier	REQ-1	2.04.07-TS-0100.001	1				
	Requirement	The sy	stem shall support dif	ferent priorities for radio access.				
	Title	Radio	Access Priorities					
	Status							
	Rationale							
	Category	<func< td=""><td>tional></td><td></td><td></td></func<>	tional>					
	Validation Method							
	Verification Method							
812								
813	[REQ Trace]							
814				REQ-06.09.03-OSED-0002.0001				
815				A-G Voice Communications				
81 <u>7</u>	10501							
818	[REQ]			-				
	Identifier	REQ-1	2.04.07-15-0100.0012	2				
	Requirement	The sy	stem shall support a p	pre-emption mechanism at the radi	o (gateway).			
		Radio	Pre-emption					
	Status							
	Rationale Radios have to be accessed in parallel by a local and remote CWP if such							
		exits Clear rules based on priorities ensure the operational correct access to a						
	0.1	snared	radio in case the loca	I and remote operator are logged I	<u>n.</u>			
	Category	<func< td=""><td>tional></td><td></td><td></td></func<>	tional>					
	Validation Method							
	Verification Method							
816								
817	[REQ Trace]			REO 06 00 03 OSED 0003 0001				
819				A-G Voice Communications				
848								
821	[REQ]							
022	Identifier	REQ-1	2.04.07-TS-0100.0013	3				
	Requirement	The system shall provide an HMI that combines A/G and G/G communication			communications			
		on one controller working position						
	Title	Combined A/G – G/G HMI						
	Status							
	Rationale							
	Category	<functional></functional>						
	Validation Method							
	Verification Method							
820	2 officiation would	1						
821	IREQ Tracel							
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<allocated_to></allocated_to>	<project></project>	12.04.07	N/A

822 823

824 3.1.1.3 Meteorological services

	•
Identifier	REQ-12.04.07-TS-0101.0001
Requirement	The RVT shall provide the ATCO/AFISO with access to the relevant meteorological information, according to ICAO Annex III and national regulations.
	Access to meteorological information

828

826

	Identifier	REQ-12.04.07-TS-0101.0002	
	Requirement	The RVT shall present continuously to the ATCO/AFISO the current MET	
		report with actual wind information and actual.	
		Current MET report	
830			
		REQ-06.09.03-OSED-0002.2002	
832			

833 3.1.1.4 Visualisation services

Identifier	REQ-12.04.07-TS-0102.0001
Requirement	The RVT <i>shall</i> provide a presentation enabling the ATCO to be provided of a continuous watch on all flight operations on and in the vicinity of an aerodrome as well as vehicles and personnel on the manoeuvring area."
	Continuous visualisation for ATCO

835 837

Identifier	REQ-12.04.07-TS-0102.0002
Requirement	The RVT shall provide a presentation enabling the AFISO to maintain a continuous watch by visual observation on all flight operations on and in the vicinity of an aerodrome as well as vehicles and personnel on the manoeuvring area.
	Continuous visualisation for AFISO

839

841

dentifier	REQ-12.04.07-TS-0102.0003
Requirement	The RVT shall provide a visualisation the ATCO/AFISO including information in order to detect obstructions on the manoeuvring area.
	Continuous visualisation for AFISO

843 845

0.40

846	[REQ]	
	Identifier	REQ-12.04.07-TS-0102.0004
	Requirement	It shall be defined how much of the "normal" tower view to be replicated
847	[REQ Trace]	

849 **3.1.1.5 Navigation services**

Identifier	REQ-12.04.07-TS-0103.0001
Requirement	The RVT shall enable the ATCO/AFISO to monitor and manoeuvre the status of the next runway and field lighting systems (visual navigational aids) applicable to the aerodrome, such as: - approach
	- PAPI
	- runway
	- taxiway
	- RGL
	- stopway
	- and obstacle lighting.

851 853

Identifier	REQ-12.04.07-TS-0103.0002
Requirement	The RVT <i>shall</i> enable the ATCO/AFISO access to adjust and monitor the
	status of aerodrome NAV systems applicable to the aerodrome (non-visual
	navigational aids), such as:
	- ILS LOC/GP,
	- LO NDB,
	- OM/MM/IM,
	- And VOR, DME.

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858 3.1.1.6 Other ATS Systems / Functions

	Identifier	REQ-12.04.07-TS-0104.0001
	Requirement	If available for the particular airport, the RVT shall include presentation of
		surveillance data (for example radar data presentation).
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- -	Lila - CC - a	
_	Identifier	REQ-12.04.07-15-0104.0002
	Requirement	The RVT shall enable access to and handling of ATS messages (as
, L		described in ICAO Doc 4444 Chapter 11)
6		
Γ	Identifier	REQ-12.04.07-TS-0104.0003
	Requirement	The RVT shall provide functions/procedures for the presentation and
	·	updating of flight plan and control data for all flights being provided with the
		ATS service (in accordance with ICAO Doc 4444 Chapter 4.13)
)		
_		
	Identifier	REQ-12.04.07-15-0104.0004
	Requirement	The RVT shall enable the ATCO/AFISO to monitor and manoeuvre acciden
		incident and distress alarms as applicable to the aerodrome.
•		
Γ	Identifier	REQ-12.04.07-TS-0104.0005
_	Requirement	The RVT shall include presentation of correct time, in the format of hours,

founding members

Identifier	REQ-12.04.07-TS-0104.0006
Requirement	The RVT <i>shall</i> enable the ATCO/AFISO (or other personnel if applicable) to
	monitor the technical status of systems that can affect the safety or efficiency
	of flight operations and/or the provision of air traffic service.

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[REQ]	
Identifier	REQ-12.04.07-TS-0104.0007
Requirement	The system shall provide means to monitor all voice communication equipment centrally from the RTC.
Title	Central VCS Monitoring
Status	
Rationale	All VCS related components, such as CWPs, radios, radio gateways, <i>shall</i> be monitored from the RTC.
Category	<functional></functional>
Validation Method	
Verification Method	

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[REQ Trace]		
	G-G Voice Communications	

885	[REQ Trace]	
886 887 886 889 8 89		G-G Voice Communications
	[REQ]	
891	Identifier	REQ-12.04.07-TS-0104.0008
892	Requirement	The system <i>shall</i> provide remote controller working position monitoring.
894	Title	Remote CWP Monitoring
895 896 897 898 899 900	Status	
	Rationale	If local CWPs at the airport or remote CWPs at the RTC may monitor each other, either for training/supervisor purposes or during the briefing before handover of responsibility.
	Category	<functional></functional>
	Validation Method	
	Verification Method	

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[REQ Trace]

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	G-G Voice Communications	

3.1.1.7 Voice and data recording services -

[REQ Trace]	
	G-G Voice Communications
3.1.1.7 Voic	e and data recording services
Identifier	REQ-12.04.07-TS-0105.0001
Requirement	The RVT shall have a voice recording system/function.
Identifier	REQ-12.04.07-TS-0105.0002
Requirement	The RVT shall have necessary data recording systems/functions
[REQ]	
Identifier	REQ-12.04.07-TS-0105.0003
Requirement	The system <i>shall</i> provide an analogue legal recording output at each CWP.
Title	Analogue Legal Recording Output at CWP

Status Rationale



Category	<functional></functional>
Validation Method	
Verification Method	

REQ-06.09.03-OSED-0002.0021 G-G Voice Communications

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[REQ Trace]

[REQ]	
Identifier	REQ-12.04.07-TS-0105.0004
Requirement	The system <i>shall</i> provide an IP legal recording output at each CWP.
Title	IP Legal Recording Output at CWP
Status	
Rationale	
Category	<functional></functional>
Validation Method	
Verification Method	

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[REQ Trace]	
	REQ-06.09.03-OSED-0002.0021
	G-G Voice Communications

909 910 911 912 **910** 914

3.1.2 Remote functional requirements 911

3.1.2.1 Visualisation services 912

Identifier	REQ-12.04.07-TS-0110.0001
Requirement	The RVT <i>shall</i> provide visual surveillance by a reproduction of the
	aerodrome view.

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Identifier	REQ-12.04.07-TS-0110.0002
Requirement	The RVT <i>may</i> enhance the visual reproduction to provide the ATCO/AFISO
	with a greater level of information and/or situational awareness.

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Identifier REQ-12.04.07-TS-0110.0003 Requirement The RVT shall include a visual reproduction configured so as to avoid unnecessary discontinuities or non-uniformities in terms of the presented scale, orientation and field of view of the area under observation by the ATCO/AFISO.		
Requirement The RVT <i>shall</i> include a visual reproduction configured so as to avoid unnecessary discontinuities or non-uniformities in terms of the presented scale, orientation and field of view of the area under observation by the ATCO/AFISO.	Identifier	REQ-12.04.07-TS-0110.0003
	Requirement	The RVT shall include a visual reproduction configured so as to avoid unnecessary discontinuities or non-uniformities in terms of the presented scale, orientation and field of view of the area under observation by the ATCO/AFISO.

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Identifier	REQ-12.04.07-TS-0110.0004
Requirement	The RVT shall adequately indicate in the visual reproduction any existing discontinuities or non-uniformities in terms of the presented scale, orientation and field of view of the area under observation by the ATCO/AFISO, so as not to cause any misleading impressions regarding the spatial geometry of the area of responsibility.

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dentifier	REQ-12.04.07-TS-0110.0005
Requirement	The RVT should provide in the visual reproduction a non-flickering
	impression to the human eye.

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Identifier	REQ-12.04.07-TS-0110.0006
Requirement	The RVT should provide a visual reproduction with smooth and regular impression of moving objects to the human eye.

Identifier	REQ-12.04.07-TS-0110.0007
Requirement	The RVT shall ensure that the time delay between image/data capture and presentation on the visual reproduction does not affect the ability to perform the ATS service.

Identifier	REQ-12.04.07-TS-0110.0008
Requirement	The RVT visual reproduction <i>shall</i> enable the ATCO/AFISO to visually
	observe an aircraft in order to satisfactorily perform the ATS service.
	When meteorological conditions and the topography of the surrounding terrain so permit, the RVT visual reproduction (presenting the manoeuvring area and the vicinity of the aerodrome) shall enable the ATCO/AFISO to visually observe an aircraft in order to satisfactorily perform the ATS service (for example on final).

Identifier	REQ-12.04.07-TS-0110.0009
Requirement	The RVT should enable the ATCO to visually judge the position of a light aircraft in the traffic pattern and in published VFR holdings.
	When meteorological conditions and the topography of the surrounding terrain so permit, the RVT should enable the ATCO to visually judge the position of a light aircraft (e.g. C172 or P28A) in the traffic pattern and in published VFR holdings.

Identifier	REQ-12.04.07-TS-0110.0010
Requirement	When meteorological conditions so permit, the RVT <i>should</i> enable the ATCO/AFISO to visually judge gear down on an aircraft in the vicinity of the aerodrome.

Identifier	REQ-12.04.07-TS-0110.0011	
Requirement	When meteorological conditions so permit, the RVT shall enable the ATCO/AFISO to visually detect irregularities during landing or take-off of aircraft that requires the ATCO/AFISO to perform any alarming services (e.g. engine fire/smoke, collapsing nose-wheel).	

Identifier	REQ-12.04.07-TS-0110.0012
Requirement	In low visibility conditions, the RVT <i>may</i> enable the ATCO/AFISO to monitor an aircraft vacating the runway.

Identifier	REQ-12.04.07-TS-0110.0013
Requirement	The RVT visual reproduction <i>may</i> incorporate features that facilitate the detection and recognition of aircraft.

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	Identifier	REQ-12.04.07-TS-0110.0014
	Requirement	The RVT visual reproduction may incorporate features that facilitate the identification of aircraft (i.e. correlation with flight plans or position reporting).
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	Identifier	REQ-12.04.07-TS-0110.0015
	Requirement	The RVT visual reproduction <i>may</i> incorporate features that facilitate tracking of aircraft (i.e. labels directly in the visual reproduction).
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	Identifier	REQ-12.04.07-TS-0110.0016
	Requirement	The RVT visual reproduction <i>may</i> incorporate features that facilitate the detection and recognition of vehicles on the manoeuvring area.
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	Identifier	REQ-12.04.07-TS-0110.0017
	Requirement	The RVT visual reproduction <i>may</i> incorporate features that facilitate the identification of vehicles on the manoeuvring area (i.e. correlation with position reporting).
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	Identifier	REQ-12.04.07-TS-0110.0018
	Requirement	The RVT visual reproduction may incorporate features that facilitate tracking of vehicles on the manoeuvring area (i.e. labels directly in the visual presentation).
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	Identifier	REQ-12.04.07-TS-0110.0019
	Requirement	The RVT visual reproduction may incorporate features that facilitate the
		detection and recognition of obstructions / foreign objects on the
		manoeuvring area (e.g. personnel or large animals).
		obstructions / toreign objects

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Identifier	REQ-12.04.07-TS-0110.0020
Requirement	The RVT visual reproduction may incorporate features that facilitate the identification of obstructions / foreign objects on the manoeuvring area (e.g. personnel or large animals).
	obstructions / foreign objects

REQ-06.09.03-OSED-0003.1409 REQ-06.09.03-OSED-0003.1410

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Identifier	REQ-12.04.07-TS-0110.0021
Requirement	The RVT visual reproduction <i>may</i> incorporate features that facilitate tracking
	of obstructions / foreign objects on the manoeuvring area (e.g. personnel or

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	large animals).
	obstructions / foreign objects
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Identifier	REQ-12.04.07-TS-0110.0022
Requirement	The RVT visual reproduction <i>may</i> incorporate features that facilitate judging aircraft position (depth of vision for the ATCO/AFISO).
	Depth of vision for the ATCO/AFISO (position)
	REQ-06.09.03-OSED-0003.1413

Identifier	REQ-12.04.07-TS-0110.0023
Requirement	The RVT visual reproduction <i>may</i> incorporate features that facilitate judging aircraft altitude
	Depth of vision for the ATCO/AFISO (altitude)

Identifier	REQ-12.04.07-TS-0110.0024
Requirement	The RVT visual reproduction <i>may</i> incorporate overlaid information to indicate specific parts of the aerodrome - such as the runway, taxiways and any building, obstruction or terrain of interest - in order to increase the ATCO/AFISO awareness of such objects in darkness or low visibility conditions.
	Visualisation of overlaid information of the aerodrome

REQ-12.04.07-TS-0110.0025
The RVT visual reproduction <i>may</i> incorporate overlaid information in order to assist the ATCO/AFISO (e.g. current wind and RVR values, status of airport systems such as runway and approach lighting),
Visualisation of overlaid information for ATCO/AFISO

Identifier	REQ-12.04.07-TS-0110.0026
Requirement	The RVT visual reproduction <i>shall</i> provide functionality corresponding to the
	binoculars in a local Tower (including a moveable zoom feature with a visual
	indication of the direction of boresight).
	Visualisation with binocular effect emulation
	REQ-06.09.03-OSED-0003.1501

Identifier	REQ-12.04.07-TS-0110.0027
Requirement	The RVT visual reproduction binocular functionality should include predefined positions (automatic functions including zoom, pan-tilt and focus).
	Visualisation with binocular effect emulation parameters

Identifier	REQ-12.04.07-TS-0110.0028
Requirement	The RVT visual reproduction binocular functionality <i>may</i> include automatic
	(pre-defined) scanning patterns.

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	Visualisation with binocular effect emulation automatic scanning patterns
Identifier	REQ-12.04.07-TS-0110.0029
Requirement	The RVT visual reproduction binocular functionality should include
	automatic tracking of aircraft, vehicles or obstructions (e.g. personnel or
	large animals).
	Visualisation with binocular effect emulation automatic tracking of aircraft
	vehicles or obstructions
Identifier	REQ-12.04.07-TS-0110.0030
Requirement	The RVT "Virtual Tower" shall provide the visualization of the remote
	aerodrome through its 3D syntetic visual reproduction
	Visualisation of 3D airport model
	TBD
Identifier	REQ-12.04.07-TS-0110.0031
Requirement	The RVT "Virtual Tower" shall provide the visualization of the ground traf
	in the remote aerodrome through the 3D virtual representation of the
	surveillance data.
	Visualization of ground traffic on remote aerodrome
lala atifi a a	
Identifier	REQ-12.04.07-TS-0110.0032
Identifier Requirement	REQ-12.04.07-TS-0110.0032 The RVT "Virtual Tower" 3D visualization of the remote aerodrome shall
Identifier Requirement	REQ-12.04.07-TS-0110.0032 The RVT "Virtual Tower" 3D visualization of the remote aerodrome shall reproduce on the virtual airport model the environmental data as day, nig
Identifier Requirement	REQ-12.04.07-TS-0110.0032 The RVT "Virtual Tower" 3D visualization of the remote aerodrome shall reproduce on the virtual airport model the environmental data as day, night rain, fog, sun position.
Identifier Requirement	REQ-12.04.07-TS-0110.0032 The RVT "Virtual Tower" 3D visualization of the remote aerodrome shall reproduce on the virtual airport model the environmental data as day, nig rain, fog, sun position. 3D virtual visualisation of the environmental data at the controlled airport
Identifier Requirement	REQ-12.04.07-TS-0110.0032The RVT "Virtual Tower" 3D visualization of the remote aerodrome shall reproduce on the virtual airport model the environmental data as day, nig rain, fog, sun position.3D virtual visualisation of the environmental data at the controlled airport

Identifier	REQ-12.04.07-TS-0111.0001
Requirement	The RVT <i>should</i> have a function for distributing the actual outdoor sound
	from the airport.
	Reproduction of actual outdoor sound from the airport

Identifier	REQ-12.04.07-TS-0111.0002
Requirement	The RVT sound reproduction volume shall be adjustable and possible to be turned off by the operator.
	Sound reproduction volume control

3.1.2.3 Other ATS systems/functions services

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Identifier	REQ-12.04.07-TS-0112.0001
Requirement	The RVT <i>should</i> include an electronic system for presentation and updating
	of flight plan and control data (in accordance with ICAO Doc 4444 Chapter



	4.13).
	Flight plan and control data presentation and updating
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1056 **3.1.2.4 Voice and data recording services**

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Identifier	REQ-12.04.07-TS-0113.0001
Requirement	The RVT voice and data recording <i>shall</i> include airport visualisation video
	data.
	Video data recording

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Identifier	REQ-12.04.07-TS-0113.0002
Requirement	The RVT voice and data recording <i>may</i> include actual outdoor sound from
	the airport, if included in the particular installation.
	Video outdoor sound recording

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1066 3.1.2.5 Work environment services

Identifier	REQ-12.04.07-TS-0114.0001
Requirement	The RVT working conditions should permit day light conditions equal to ordinary office establishments.
	Working conditions - light

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Identifier	REQ-12.04.07-TS-0114.0002
Requirement	The RVT working environment (noise, temperature etc) shall be according
	national regulations for normal office establishments.
	Working conditions – environment regulations

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1075 **3.1.3 Additional functional requirements for multiple TWRs**

1076 Depending on the evolution of the requirements of the 6.4 chapter of the OSED. (ref[8]).

3.1.4 Additional functional requirements for contingency

1078 Depending on the evolution of the requirements of the 6.4 chapter of the OSED (ref[8]).

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1080 **3.2 Adaptability**

1081 3.2.1 Modularity Requirements

Identifier	REQ-12.04.07-TS-0201.0001
Requirement	The RVT design shall be modular in the sense that no major design change shall be necessary to meet specific operational requirements of an aerodrome.

Identifier	REQ-12.04.07-TS-0201.0002
Requirement	The RVT equipment <i>shall</i> comprise hardware and software modules.

1089		
1000	Identifier	REQ-12.04.07-TS-0201.0003
	Requirement	The RVT consists of many elements which, when integrated, are designed to meet the specific operational requirements of an aerodrome. In order to cover a wide range of requirements any element design should comply with the modularity concept.
1091		
1093	Identifier	REO-12 04 07-TS-0201 0004
	Requirement	The RVT shall be modular so that the appropriate level of service can be
		provided to different aerodromes as well as to different areas of an aerodrome.
1095	<u></u>	
1097		
1098		
1099	[REQ]	REO 12 04 07 TS 0201 0005
	Requirement	The RVT system shall be modular with respect to applications, such as
	Requirement	Aerodrome Surveillance, Flight Data Processing, Voice Communication System, Information & Control and Visual Reproduction.
	Title	Modular Applications
	Status	
	Rationale	The customer shall be able to choose any combination of applications
		necessary to fulfil its operational needs.
	Category	<functional></functional>
	Validation Method	
4400	Verification Method	
1100		
1102		G-G Voice Communications
1102		
1183	[REQ]	
1106	Identifier	REQ-12.04.07-TS-0201.0006
1107	Requirement	The RVT system <i>shall</i> be modular allowing procurement of modules from different suppliers.
1110	Title	Modular Vendors
1111	Status	
1112 1113 1114	Rationale	The customer shall be able to choose any combination of vendors necessary to fulfil its operational needs.
1115	Category	<functional></functional>
1116	Validation Method	
4404	Verification Method	
1104	[REQ Trace]	
1106		G-G Voice Communications
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1117 1118		
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3.2.2 Scalability Requirements 1107

Identifier	REQ-12.04.07-TS-0202.0001	
Requirement	The RVT shall be such that further components can be added in order to	
	expand the system in terms of functionality and numbers of users	
Identifier	REQ-12.04.07-TS-0202.0002	
Requirement	The modules shall be such that the RVT can be dimensioned according to	
	the needs of different aerodromes.	
IREO1		
Identifier	REO-12 04 07-TS-0202 0003	
Requirement	The system shall be scalable with respect to voice communication equipment	
rtoquironioni	(radios, radio gateways, controller working positions).	
Title	VCS Equipment Scalability	
Status		
Rationale	The need to add an additional radio, radio gateway, or working position shall	
	not cause the whole system to be replaced.	
Category	<functional></functional>	
Validation Method		
Verification Method		
[REQ Trace]		
	G-G Voice Communications	
Identifier	REO-12 04 07-TS-0202 0004	
Requirement	The system shall be scalable with respect to operated airports/beliports	
Title	Operated Airport Scalability	
Status		
Rationale	The need to add an additional airport to be operated from a RTC shall not	
	cause the whole system to be replaced, but only additional components to be	
	added.	
Category	<functional></functional>	
Validation Method		
Verification Method		
[REQ Trace]		
	G-G Voice Communications	
	ilite Demoiser en te	
3.2.3 Adaptability Requirements		
Identifier	REQ-12.04.07-TS-0203.0001	
Requirement	Adaptation of the equipment to different local site configurations, procedures	
	and working methods shall be done through an appropriate database	
	(sensor positions, airport topography/topology, etc.).	
Identifier	REQ-12.04.07-TS-0203.0002	
Requirement	The RVT services shall be configurable to adapt to local ATC procedures	
	and working methods.	

Identifier	REQ-12.04.07-TS-0203.0003
Requirement	The RVT design shall take into account the working environment of the user under various operational conditions. In this respect, the RVT working positions shall be adaptable to the various circumstances of the user. Note: As an example, good visibility operations with high traffic throughput will require a different A-SMGCS set-up than that required for low visibility operations with reduced throughput.

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Identifier	REQ-12.04.07-TS-0203.0004	
Requirement	The system <i>shall</i> provide a role management system that unites all functions	
	in CWP.	
Title	Role Management	
Status		
Rationale		
Category	<functional></functional>	
Validation Method		
Verification Method		

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[REQ Trace]

1143	[REQ Trace]		
1144 1145 1145		G-G Voice Communications	
	[REQ]		
1148	Identifier	REQ-12.04.07-TS-0203.0005	
1149 1150	Requirement	The role system <i>shall</i> be independent from the physical controller working position.	
1151	Title	Role Management Independent from CWP	
1153	Status		
1154 1155 1156 1157 1158	Rationale	A role can be selected at any given CWP, especially necessary when local and remote operations are possible.	
	Category	<functional></functional>	
	Validation Method		
	Verification Method		
1146	-		

3.2.4 Configurability Requirements

[REQ Trace]		
	G-G Voice Communications	
3.2.4 Configurability Requirements		
Identifier	REQ-12.04.07-TS-0204.0001	
Requirement	The RVT visualisation shall be configurable in order to accommodate any change in the layout of the aerodrome (runways, taxiways and aprons), vithout modifying the core processing.	
	[REQ Trace] 3.2.4 Configu Identifier Requirement	

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[KEQ]	
Identifier	REQ-12.04.07-TS-0204.0002
Requirement	The system <i>shall</i> provide means to define the radio layout (HMI).
Title	Radio Layout Configuration
Status	
Rationale	Operating airports flexible requires different radio layouts.
Category	<functional></functional>
Validation Method	
Verification Method	



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[REQ Trace]		
	A-G Voice Communications	
[REQ]		
Identifier	REQ-12.04.07-TS-0204.0003	
Requirement	The system <i>shall</i> provide means to define the phone layout (HMI).	
Title	Phone Layout Configuration	
Status		
Rationale	Operating airports flexible requires different phone layouts.	
Category	<functional></functional>	
Validation Method		
Verification Method		

[REQ Trace]

REQ-06.09.03-OSED-0002.0001
A-G Voice Communications

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3.3 Performance Characteristics 1166

3.3.1 Capacity Requirements 1167

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	Identifier	REQ-12.04.07-TS-0301.0001		
	Requirement	The amount of access to aeronautical mobile service (air-ground communications) shall be specified for the RVT.		
1170 1172				
	Identifier	REQ-12.04.07-TS-0301.0002		
	Requirement	The amount of access to aeronautical mobile service (ground-ground communications) <i>shall</i> be specified for the RVT.		
1174 1176				
	Identifier	REQ-12.04.07-TS-0301.0003		
	Requirement	What capabilities the RVT CWP must provide <i>should</i> be specified.		
1179 1180 1182				
	Identifier	REQ-12.04.07-TS-0301.0004		
	Requirement	It shall be defined how much of the "normal" tower view to be replicated		
1184 1186 1187				
	Identifier	REQ-12.04.07-TS-0301.0005		
	Requirement	The 3D System Viewer in RVT "virtual tower" <i>shall</i> be capable of interpreting received High Level Architecture (HLA) 1516 data or Distributed Interactive Simulation (DIS) data in order to provide a user with real time 3D visualisation that is representative of the received data.		
1189				

Identifier	REQ-12.04.07-TS-0301.0006
Requirement	The 3D System Viewer in RVT "virtual tower" shall be able to provide
	representative visualisation of visibility range, wind speed, wind direction, j



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Identifier	REQ-12.04.07-TS-0301.0007
Requirement	The RVT <i>shall</i> provide a DR&A to record and playback the last TBD minutes of the complete RVT data. Air to Ground communications, Ground to Ground communications, Surveillance data, live video OTW, DIS/HLA entities for 3D Visualizer.

cloud cover, cloud height, rain, snow.

3.3.2 Accuracy Requirements

	Identifier	REQ-12.04.07-TS-0302.0001
	Requirement	The remoted video OTW Viewer in RVT "remote tower" shall provide a
		visual detail that match OTW direct vision.
205		
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208		
	Identifier	REQ-12.04.07-TS-0302.0002
	Requirement	The 3D System Viewer in RVT "virtual tower" shall provide a visual detail
		that match OTW direct vision.
210		
212		
	Identifier	REQ-12.04.07-TS-0302.0003
	Requirement	The 3D System Viewer in RVT "virtual tower" shall allow a user to reduce
		the visualised detail of Entities in order to improve run time performance of
		the 3D System Viewer.
214		

3.3.3 Timing performances Requirements

Identifier	REQ-12.04.07-TS-0303.0001
Requirement	The RVT shall provide the ATCO/AFISO with access to aeronautical mobile service (air-ground communications) and to aeronautical fixed service (ground-ground communications) with a maximum delay that shall be specified in the implementation requirement specification

Identifier	REQ-12.04.07-TS-0303.0002
Requirement	The RVT shall provide the ATCO/AFISO with live video images of the OTW in he remote controlled aerodrome with a maximum delay that shall be specified in the implementation requirement specification.

Identifier	REQ-12.04.07-TS-0303.0003
Requirement	The RVT shall provide the CWP with surveillance data from the remote controlled aerodrome with a maximum delay that shall be specified in the

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D05 - Single Remote Tower	Technical Specifications

		implementation requirement specification.
228	L	·
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200	Identifier	REQ-12.04.07-TS-0303.0004
	Requirement	The RVT shall provide the 3D viewer with surveillance data from the remote controlled aerodrome with a maximum delay that shall be specified in the implementation requirement specification.
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	Identifier	REQ-12.04.07-TS-0303.0005
	Requirement	The RVT 3D viewer shall provide the virtual 3D visualization of ground traffic on the remote airport with a maximum delay that shall be specified in the implementation requirement specification
3		· ·
)		
	Identifier	REQ-12.04.07-TS-0303.0006
	Requirement	In case of a single fault the RVT shall provide an automatic reconfiguration in order to resume the service in less than TBD seconds.
	Identifier	REQ-12.04.07-TS-0303.0007
	Requirement	The RVT shall sustain at least for TBD minutes a temporary workload exceeding its maximum standard workload by TBD %
5	IREQI	
•	Identifier	REQ-12.04.07-TS-0303.0008
	Requirement	The RVT shall ensure that the time delay variation between image capture and presentation on the visual reproduction <i>does n</i> ot differ in a way that it affects the ability to perform the ATS service.
		REQ-06.09.03-OSED-0003.1106
9 0	[REQ Trace]	
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1252 3.3.4 Software and resource usage Requirements

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Identifier	REQ-12.04.07-TS-0304.0001
Requirement	Specify the resolution requirements
	Horizontal resolution depends on field of view angle
	resolution must be defined in requirement based on these

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Identifier	REQ-12.04.07-TS-0304.0002
Requirement	The 3D System Viewer in RVT "virtual tower" <i>shall</i> be capable of visualising within a 3D scenario environment the same number of 3D object models as tracks in the CWP up to the max. tracks number

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1263		
	Identifier	REQ-12.04.07-TS-0304.0003
	Requirement	The 3D System Viewer in RVT "virtual tower" <i>shall</i> be capable of refreshing its 3D Visualisation Window at a rate of 30Hz +/- a 25% tolerance.
1265		
1267		
1268	Identifier	DEO 12 04 07 TS 0204 0004
	Identiller	REQ-12.04.07-15-0304.0004
	Requirement	The Presentation System Viewer in RVT "remote tower" shall be capable of
		refreshing images at a rate of 30Hz +/- a 25% tolerance.
1270		
1271		
1272		
1273		
1274		
	Identifier	REQ-12.04.07-TS-0304.0005
	Requirement	The RVT hardware/software usage shall be lower than 60% of the maximum
		available resoureces when running a load scenario
1276		· · · · · · · · · · · · · · · · · · ·
1278		
1210		
	Identifier	REQ-12.04.07-TS-0304.0006
	Requirement	The RVT 3D visualization system hardware/software usage shall be lower
		than 60% of the maximum available resources when running a load
		scenario.

3.3.5 Overload tolerance Requirements

nporary workload exceeding a percent its d, that percent shall be specified in the specification
: :

3.4 Safety & Security

1289 It is expected that 6.9.3 project delivers a safety assessment which is under work.

1290 The following requirements should be fulfilled as minimum requirements for a prototype.

[REQ]	
Identifier	REQ-12.04.07-TS-0306.0001
Requirement	The system <i>shall</i> be fail-safe
Title	Fail-safe system
Status	
Rationale	The term "fail-safe" in this context means that sufficient redundancy is provided to carry data to the display equipment to permit some components of the equipment to fail without any resultant loss of data displayed
Category	<non functional=""></non>
Validation Method	
Verification Method	

[REQ Trace]



Z

1295	[REQ]	
	Identifier	REQ-12.04.07-TS-0306.0002
	Requirement	The system shall be fail-soft
	Title	Fail-soft system
	Status	
	Rationale	The term "fail-soft" means that the system is so designed that, even if equipment fails to the extent that loss of some data occurs, sufficient data remain on the display to enable the controller to continue operations
	Category	<non functional=""></non>
	Validation Method	
	Verification Method	
1296 1297 1298 1 299	[REQ Trace]	
1300	[REQ]	
1302	Identifier	REO-12 04 07-TS-0306 0003
1303 1304	Requirement	Specify the need for redundancy for the system so that a failure on any part of the system should not lead to a fall-off of the service
1305	Title	redundancy
1307	Status	
1308	Rationale	
1309	Category	<non functional=""></non>
1311	Validation Method	
1312	Verification Method	
1313	vermeation method	
1305 1308	[REQ Trace]	
1 30 2 1308		
1309		
1300	Identifier	REQ-12.04.07-1S-0306.0004
1308	Requirement	All critical elements of the system should be provided with timely audio and/or visual indications of failure
1320	Title	Indication of failure
1325	Status	
1320	Rationale	
1328	Category	<non functional=""></non>
1315	Validation Method	
1316	Verification Method	
1317	Vermodileri Method	
1309 1306 1306 1308 1308	[REQ Trace]	
1320	Identifier	REQ-12.04.07-TS-0306.0005
1320 1320 1323	Requirement	The system design <i>should</i> preclude failures that result in erroneous data for operationally significant time periods
1328	Title	Design constraint
1329	Status	
1330	Rationale	
1318	Category	<non functional=""></non>
1319	Validation Method	
1320	Verification Method	
1328 1329 1329 1329	[REQ Trace]	
132Ø 1923 1328 1329 1330	[REQ]	
1337 1338 1339 1320 1325	founding members	Avenue de Cortenbergh 100 B- 1000 Bruxelles www.sesarju.eu 53 of 72
1044		

REQ-12.04.07-TS-0306.0006
The system <i>should</i> have the ability to provide continuous validation of data and timely alerts to the user when the system must not be used for the intended operation. The validity of data should be assessed by the system in accordance with the assigned priority given to these data
Validation of data
<non functional=""></non>

[REQ Trace]

1315

[REQ]	
Identifier	REQ-12.04.07-TS-0306.0007
Requirement	A self-checking system with failure alerts <i>should</i> be included in the system
	design.
Title	self-checking
Status	
Rationale	
Category	<non functional=""></non>
Validation Method	
Verification Method	

[REQ Trace]

[REQ]

Identifier	REQ-12.04.07-TS-0306.0008
Requirement	The system shall follow Safety Case according to Eurocontrol SAMv2.1
Title	Safety Case
Status	
Rationale	
Category	<non functional=""></non>
Validation Method	
Verification Method	

[REQ Trace]

[REQ]

Identifier	REQ-12.04.07-TS-0306.0009
Requirement	The system <i>shall</i> support authentication in its components for management
	access.
Title	Authentication for Management Access
Status	
Rationale	
Category	<functional></functional>
Validation Method	
Verification Method	

[REQ Trace]

	A-G	Voice	Communications
-			

[REQ]	
Identifier	REQ-12.04.07-TS-0306.0010
Requirement	The system shall support confidentiality in its components for management

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THE	Confidentiality for Management Access
Status	
Rationale	
	< Functional>
Validation Mothod	
Validation Nethod	
venincation method	
[REQ Trace]	A-G Voice Communications
[REQ]	
Identifier	REQ-12.04.07-TS-0306.0011
Requirement	The system shall support authentication at each controller working position
Title	Authentication for CWP
Status	
Pationale	
	< Functionals
Validation Mathed	
vernication wethod	
	A-G Voice Communications
	A-9 Voice communications
[NLQ] Identifier	REO 12.04.07 TS 0206 0012
Dequirement	REQ-12.04.07-13-0300.0012
Requirement	The radio gateway shall only allow access from known clients (white list).
	Radio Gateway White List
Status	
Rationale	
Category	<functional></functional>
Validation Method	
Verification Method	
[REQ Trace]	
	A-G Voice Communications
[REQ] Identifier Requirement Title	REQ-12.04.07-TS-0306.0013 The system <i>shall</i> support monitoring mechanisms that ensures confidentia Monitoring Confidentiality
Status	
Rationale	
Category	<functional></functional>
Validation Method	
Verification Method	
[REQ Trace]	A-G Voice Communications
[REQ] Identifier Requirement	REQ-12.04.07-TS-0306.0014 The system <i>shall</i> support monitoring mechanisms that ensures integrity.
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Title	Monitoring Integrity
Status	
Rationale	
Category	<functional></functional>
Validation Method	
Verification Method	

1346

[REQ Trace]

1347 1348 1349 1350 1351 1353 1353 1355 1356 1357 1358	[REQ Trace]	
		A-G Voice Communications
	[REQ]	
	Identifier	REQ-12.04.07-TS-0306.0015
	Requirement	The system <i>shall</i> support monitoring mechanisms that provides authentication.
	Title	Monitoring Authentication
	Status	
	Rationale	
1360	Category	<functional></functional>
1361	Validation Method	
1362	Verification Method	
1350		

3.5 Maintainability

51 52 53	[REQ Trace]	A-G Voice Communications
1354 1355 1356 1358 1359 1360 1361 1362	3.5 Maintainability	
	Identifier	REQ-12.04.07-TS-0307.0001
	Requirement	Requirements regarding maximum downtime for total OTW <i>shall</i> be specified.
5 4		Downtime for total OTW
5		

Identifier	REQ-12.04.07-TS-0307.0002
Requirement	Requirements regarding maximum downtime for a single OTW monitor <i>shall</i> be specified.
	downtime for a single OTW monitor
	downtime for a single OTW monitor

1359 1361

Identifier	REQ-12.04.07-TS-0307.0003
Requirement	Requirements regarding maximum downtime for PTZ shall be specified.
	downtime for PTZ

1363

1	365	

1367 1369

Identifier	REQ-12.04.07-TS-0307.0004
Requirement	Requirements regarding maximum downtime for communication between RTC and airport <i>shall</i> be specified.
	downtime for communication between RTC and airport

REQ-12.04.07-TS-0307.0005 Identifier



Requirement	Requirements regarding maximum downtime for total system and sub- system shall be specified.
	downtime for total system and sub-system

1374 3.6 Reliability

Identifier	REQ-12.04.07-TS-0308.0001
Requirement	Requirements regarding maximum MTBF for total OTW <i>shall</i> be specified.
	maximum MTBF for total OTW

Identifier	REQ-12.04.07-TS-0308.0002
Requirement	Requirements regarding maximum MTBF for a single OTW monitor <i>shall</i> be specified.
	maximum MTBF for a single OTW

Identifier	REQ-12.04.07-TS-0308.0003
Requirement	Requirements regarding maximum MTBF for PTZ shall be specified
	maximum MTBF for PTZ

Identifier	REQ-12.04.07-TS-0308.0004
Requirement	Requirements regarding maximum MTBF for XXX shall be specified
	maximum MTBF for XXX

Identifier	REQ-12.04.07-TS-0308.0005
Requirement	The RVT <i>shall</i> provide the ATCO with warning indicating if picture is frozen.

Identifier	REQ-12.04.07-TS-0308.0006
Requirement	The RVT <i>shall</i> provide the ATCO with warning indicating if picture is corrupt.

Identifier	REQ-12.04.07-TS-0308.0007
Requirement	The RVT <i>shall</i> provide the ATCO with warning indicating if picture is delayed.

Identifier	REQ-12.04.07-TS-0308.0008
Requirement	Requirements regarding maximum delay for picture in OTW <i>shall</i> be specified.
	maximum delay for picture in OTW

1403

1405

1406 3.7 Functional block Internal Data Requirements

1407 Requirements regarding internal data structure should be specified in the implementation specific 1408 requirements specification.

1409 3.8 Design and Construction Constraints

1410

1411 [REQ]

Identifier	REQ-12.04.07-TS-0309.0001
Requirement	All constructions at the local airport should follow the guidelines defined in the
	applicable ICAO Standards (e.g. Annex 14)
Title	Airport Constructions
Status	
Rationale	
Category	<functional></functional>
Validation Method	
Verification Method	
[REQ Trace]	

1412 1413

1414 [REQ]

Identifier	REQ-12.04.07-TS-0309.0002
Requirement	All major system components shall be decoupled and separated by clear
	defined interfaces.
Title	Modular Design
Status	
Rationale	
Category	<functional></functional>
Validation Method	
Verification Method	
[REQ Trace]	

1415 1416

1417 [REQ]

Identifier	REQ-12.04.07-TS-0309.0003
Requirement	The system construction <i>shall</i> utilize COTS hardware products.
Title	Modular Design
Status	
Rationale	Provide flexibility in terms of hardware procurement and avoid bespoken
	hardware solution.
Category	<functional></functional>
Validation Method	
Verification Method	
[REQ Trace]	

1418 [REC

1419

1420 [REQ]

Identifier

REQ-12.04.07-TS-0309.0004



Requirement	Network QoS monitoring and usage shall be taken into account in the design of system function.
Title	QoS monitoring
Status	
Rationale	Some critical RVT functionalities rely on wide-area network capacity. So the network in this case could be subject to degradation which has an immediate impact on operation unlike systems based solely on local network which are by construction more predictable. Possibly some function could automatically decide to self-deactive because the quality of the information they use is not good enough to be processed and would provide the user with bad quality information which can lead to wrong decisions.
Category	<functional></functional>
Validation Method	
Verification Method	
IPEO Tracol	

1421 [REQ Trace]

1422

1423 [REQ]

[IVE Q]	
Identifier	REQ-12.04.07-TS-0309.0005
Requirement	The design shall allow the distribution of the network traffic to different
	communication infrastructure or providers.
Title	Modular Design
Status	
Rationale	This provides service contingency in case of network provider failure (for example having data trafficking in one infrastructure, and voice (VoIP) through another one)
Category	<functional></functional>
Validation Method	
Verification Method	

1424 [REQ Trace]

1425

1426 3.9 Functional block Interface Requirements

1427

1428 The remote tower system design consists of two parts. The core system in the RTC and a local proxy 1429 at the dedicated airport. These parts are connected via a wide area network which might be provided 1430 by an external partner (telco ...). This WAN interface is not considered as an external interface from a 1431 logical point of view.

1432 External interfaces are situated at the local airport or at the RTC. Dependant on the detailed 1433 implementation some of these interfaces and the systems/sensors behind might be included in the 1434 remote tower solution (e.g., cameras, VHF radios). In other cases such sensor might already be 1435 existing and will be integrated into the remote tower system. Such interfaces are considered as 1436 optional.

1437



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1439 1440

1441 [REQ]

REQ-12.04.07-TS-0310.0001
The design shall allow local or centralized deployment of interfaces
Interface Surveillance Sensors
Some interfaces could be provided locally or directly at the remote TWR site.
The design shall not constraint a certain deployment solution.
<functional></functional>

1442

1443 [REQ Trace]

1444

1445 [REQ]

[···=]	
Identifier	REQ-12.04.07-TS-0310.0002
Requirement	The system <i>shall</i> provide an interface to local surveillance sensors.
Title	Interface Surveillance Sensors
Status	
Rationale	
Category	<functional></functional>
Validation Method	
Verification Method	

1446

1447 [REQ Trace]

Identifier

1448

1449 [REQ]

REQ-12.04.07-TS-0310.0003



Requirement	The system shall shall provide an interface to local cameras. Applicable standard e.g.
	ONVIF could be supported
Title	Interface Camera
Status	
Rationale	
Category	<functional></functional>
Validation Method	
Verification Method	

1450

1451 [REQ Trace]

1452

1453

Identifier REQ-12.04.07-TS-0310.0004 Requirement The system shall provide an interface to local VHF radios via analogue interface or IP (compliant to ED137). Title Interface Radios Status Rationale
Requirement The system shall provide an interface to local VHF radios via analogue interface or IP (compliant to ED137). Title Interface Radios Status Rationale
interface or IP (compliant to ED137). Title Interface Radios Status Rationale
Title Interface Radios Status Rationale
Status Rationale
Rationale
Category <- Functional>
Validation Method
Verification Method

1454 1455

55 [REQ Trace]

1456

1457

[REQ]	
Identifier	REQ-12.04.07-TS-0310.0005
Requirement	The system <i>shall</i> provide an interface to local airport systems such as Airfield
	Lights, Met System and Nav Aids.
Title	Interface Airport Systems
Status	
Rationale	
Category	<functional></functional>
Validation Method	
Verification Method	

1458

1459 [REQ Trace]

1460 1461

[REQ]	
Identifier	REQ-12.04.07-TS-0310.0006
Requirement	The system may provide an interface to specific partners at the local airport (e.g. Airport Operator) allowing read-only access to information the RTS can provider,
Title	Interface
Status	
Rationale	
Category	<functional></functional>
Validation Method	
Verification Method	

1462 1463 [REQ Trace]

1464

[REQ]	
Identifier	REQ-12.04.07-TS-0310.0007
Requirement	The system <i>shall</i> provide a central interface for telephone lines
Title	Interface Phone
Status	



Rationale	
Category	<functional></functional>
Validation Method	
Verification Method	

1466

[REQ Trace]

1467 1468

1469 [REQ]

[···= ~]	
Identifier	REQ-12.04.07-TS-0310.0008
Requirement	The system shall provide a central interface to the SWIM network for services
	MET, Flight Plan, Surveillance and AIM
Title	Interface SWIM
Status	
Rationale	
Category	<functional></functional>
Validation Method	
Verification Method	

1470

1471 [REQ Trace]

1472 1473 [RFQ]

Identifier	REQ-12.04.07-TS-0310.0009
Requirement	The system <i>shall</i> provide a central interface to the AFTN or other legacy FDP systems for flight data exchange.
Title	Interface AFTN, FDP
Status	
Rationale	
Category	<functional></functional>
Validation Method	
Verification Method	

1474

1475 [REQ Trace]

1476

1477 [REQ]

Identifier	REQ-12.04.07-TS-0310.0010
Requirement	The system should provide a central interface to FDP systems in order to exchange sectorization data
Title	Interface FDP or SWIM if available
Status	
Rationale	The RTS shall inform or being informed about the airfields (and thus jurisdiction) it takes overs.
Category	<functional></functional>
Validation Method	
Verification Method	

1478 1479 [REQ Trace]

1480

[REQ]	
Identifier	REQ-12.04.07-TS-0310.0011
Requirement	IP-based voice communication and recording shall be compliant with EUROCAE Working Group 67 recommendations.
Title	EUROCAE Compliant
Status	
Rationale	
Category	<functional></functional>
Validation Method	
Verification Method	



1482 1483	[REQ Trace]	
1484		
1485		
1486		



1488 **4** Assumptions

1489 It is assumed that this document is generic and will serve as a basis for the creation of a requirement 1490 specification

- 1491 In this first iteration, only Single Remote Tower has been taken into account.
- Next iteration Iteration 2, will focus on the finalizing of the Single Remote Tower draft and produce the first draft of the Multiple Remote Tower
- 1494



5	References
	[1] SESAR PMP 02.00.00
	[2] Template Toolbox 02.00.00
	[3] Requirements and V&V Guidelines 02.00.00
	[4] Toolbox User Manual 02.00.00
	 [5] SESAR Definition Phase – Task 2.4.x Milestone 3 – System Architecture (DLT-0612-244-00- 10), September 2007
	[6] IEEE / MIL Standards
	[7] Architecture of the Technical Systems Description Document for Step 1. (B.04.03-D09-00- ADD_ 20110511.doc)
	5

- 1506 [8] Project 06.09.03 Operational Service and Environment Definition (OSED) Ed 00.02.01
- 1507

1508 5.1 Use of copyright / patent material /classified material 1509 (NATMIG)

1510 This document needs no prior consent of copyright and patent owner.

1511 5.1.1 Classified Material (NATMIG)

1512 There is no sensitive information contained in this technical specification.



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1513 Appendix A Traceability

- 1514 This section presents the traceability matrices, which identify, for every TS requirement:
- The key elements of the TS requirement (identifier and title),
- The ATMS Requirement that the TS requirement satisfies,
- The higher level requirement that the TS requirement satisfies (identifier and title).
- 1518 These traceability matrices enable to check the coverage.

TS Requirement		Satisfied Requirement / Enabler	
Identifier	Title	Identifier	Title
	General functional	requirements	
REQ-12.04.07-TS-0100.0001	Air-ground communications	REQ-06.09.03-OSED-0002.1001	
REQ-12.04.07-TS-0100.0002	Ground-ground communications	REQ-06.09.03-OSED-0002.1002	
REQ-12.04.07-TS-0100.0003	Ground-ground vehicle communications	REQ-06.09.03-OSED-0002.1003	
REQ-12.04.07-TS-0100.0004	Signalling lamp functionality	REQ-06.09.03-OSED-0002.1004	
REQ-12.04.07-TS-0100.0005	Visual communication from aircraft	REQ-06.09.03-OSED-0002.1005	
REQ-12.04.07-TS-0100.0006	Visual communication from aircraft on manoeuvring area		
REQ-12.04.07-TS-0100.0007	Surveillance data from remote controlled airport		
REQ-12.04.07-TS-0100.0008	Voice Communications Network Performance		
REQ-12.04.07-TS-0100.0009	Hierarchical Side Tone Generation	REQ-06.09.03-OSED-0002.0001	X
REQ-12.04.07-TS-0100.0010	Shared Radio Access		X
REQ-12.04.07-TS-0100.0011	Radio Access Priorities	REQ-06.09.03-OSED-0002.0001	Х
REQ-12.04.07-TS-0100.0012	Radio Pre-emption	REQ-06.09.03-OSED-0002.0001	x
REQ-12.04.07-TS-0100.0013	Combined A/G – G/G HMI	REQ-06.09.03-OSED-0002.0001 REQ-06.09.03-OSED-0002.0002	



REQ-12.04.07-TS-0101.0001 Access to meteorological information REQ-12.04.07-TS-0101.0002 Current MET report REQ-06.09.03-OSED-0002.2002 REQ-12.04.07-TS-0102.0001 Continuous visualisation for ATCO REQ-12.04.07-TS-0102.0002 Continuous visualisation for AFISO REQ-12.04.07-TS-0102.0003 Continuous visualisation for AFISO REQ-12.04.07-TS-0102.0004 REQ-12.04.07-TS-0103.0001 REQ-12.04.07-TS-0103.0002 REQ-12.04.07-TS-0104.0001 REQ-12.04.07-TS-0104.0002 REQ-12.04.07-TS-0104.0003 REQ-12.04.07-TS-0104.0004 REQ-12.04.07-TS-0104.0005 REQ-12.04.07-TS-0104.0006 REQ-12.04.07-TS-0104.0007 Central VCS Monitoring REQ-12.04.07-TS-0104.0008 Remote CWP Monitoring REQ-12.04.07-TS-0105.0001 REQ-12.04.07-TS-0105.0002 REQ-12.04.07-TS-0105.0003 Analogue Legal Recording Output at CWP REQ-06.09.03-OSED-0002.0021 IP Legal Recording Output at CWP REQ-12.04.07-TS-0105.0004 REQ-06.09.03-OSED-0002.0021 REQ-12.04.07-TS-0110.0001 REQ-12.04.07-TS-0110.0002 REQ-12.04.07-TS-0110.0003 REQ-12.04.07-TS-0110.0004 REQ-12.04.07-TS-0110.0005 REQ-12.04.07-TS-0110.0006 REQ-12.04.07-TS-0110.0007 REQ-12.04.07-TS-0110.0008



REQ-12.04.07-TS-0110.0009		
REQ-12.04.07-TS-0110.0010		
REQ-12.04.07-TS-0110.0011		
REQ-12.04.07-TS-0110.0012		
REQ-12.04.07-TS-0110.0013		
REQ-12.04.07-TS-0110.0014		
REQ-12.04.07-TS-0110.0015		
REQ-12.04.07-TS-0110.0016		
REQ-12.04.07-TS-0110.0017		
REQ-12.04.07-TS-0110.0018		
REQ-12.04.07-TS-0110.0019	obstructions / foreign objects	
REQ-12.04.07-TS-0110.0020	obstructions / foreign objects	
REQ-12.04.07-TS-0110.0021	obstructions / foreign objects	
REQ-12.04.07-TS-0110.0022	Depth of vision for the ATCO/AFISO (position)	
REQ-12.04.07-TS-0110.0023	Depth of vision for the ATCO/AFISO (altitude)	
REQ-12.04.07-TS-0110.0024	Visualisation of overlaid information of the aerodrome	
REQ-12.04.07-TS-0110.0025	Visualisation of overlaid information for ATCO/AFISO	
REQ-12.04.07-TS-0110.0026	Visualisation with binocular effect emulation	
REQ-12.04.07-TS-0110.0027	Visualisation with binocular effect emulation parameters	
REQ-12.04.07-TS-0110.0028	Visualisation with binocular effect emulation automatic scanning patterns	
REQ-12.04.07-TS-0110.0029	Visualisation with binocular effect emulation automatic tracking of aircraft, vehicles or obstructions	
REQ-12.04.07-TS-0110.0030	Visualisation of 3D airport model	



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REQ-12.04.07-TS-0110.0031 Visualization of ground traffic on remote aerodrome REQ-12.04.07-TS-0110.0032 3D virtual visualisation of the environmental data at the controlled airport REQ-12.04.07-TS-0111.0001 Reproduction of actual outdoor sound from the airport REQ-12.04.07-TS-0111.0002 Sound reproduction volume control REQ-12.04.07-TS-0112.0001 Flight plan and control data presentation and updating REQ-12.04.07-TS-0113.0001 Video data recording Video outdoor sound recording REQ-12.04.07-TS-0113.0002 Working conditions - light REQ-12.04.07-TS-0114.0001 REQ-12.04.07-TS-0114.0002 Working conditions – environment regulations Adaptability REQ-12.04.07-TS-0201.0001 REQ-12.04.07-TS-0201.0002 REQ-12.04.07-TS-0201.0003 REQ-12.04.07-TS-0201.0004 REQ-12.04.07-TS-0201.0005 Modular Applications REQ-12.04.07-TS-0201.0006 Modular Vendors REQ-12.04.07-TS-0202.0001 REQ-12.04.07-TS-0202.0002 VCS Equipment Scalability REQ-12.04.07-TS-0202.0003 **Operated Airport Scalability** REQ-12.04.07-TS-0202.0004 REQ-12.04.07-TS-0203.0001 REQ-12.04.07-TS-0203.0002 REQ-12.04.07-TS-0203.0003 REQ-12.04.07-TS-0203.0004 Role Management



REQ-12.04.07-TS-0203.0005	Role Management Independent from CWP		
REQ-12.04.07-TS-0204.0001			
REQ-12.04.07-TS-0204.0002	Radio Layout Configuration		
REQ-12.04.07-TS-0204.0003	Phone Layout Configuration	REQ-06.09.03-OSED-0002.0001	
	Preformance Cha	racteristics	
REQ-12.04.07-TS-0301.0001			
REQ-12.04.07-TS-0301.0002			
REQ-12.04.07-TS-0301.0003			
REQ-12.04.07-TS-0301.0004			
REQ-12.04.07-TS-0301.0005			
REQ-12.04.07-TS-0301.0006			
REQ-12.04.07-TS-0301.0007			
REQ-12.04.07-TS-0302.0001			
REQ-12.04.07-TS-0302.0002			
REQ-12.04.07-TS-0302.0003			
REQ-12.04.07-TS-0303.0001			
REQ-12.04.07-TS-0303.0002			
REQ-12.04.07-TS-0303.0003			
REQ-12.04.07-TS-0303.0004			
REQ-12.04.07-TS-0303.0005			
REQ-12.04.07-TS-0303.0006			
REQ-12.04.07-TS-0303.0007			
REQ-12.04.07-TS-0303.0008			
REQ-12.04.07-TS-0304.0001			
REQ-12.04.07-TS-0304.0002			
REQ-12.04.07-TS-0304.0003			
REQ-12.04.07-TS-0304.0004			
REQ-12.04.07-TS-0304.0005			



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REQ-12.04.07-TS-0304.0006			
REQ-12.04.07-TS-0305.0001			
	Safety & Sec	urity	
REQ-12.04.07-TS-0306.0001	Fail-safe system		
REQ-12.04.07-TS-0306.0002	Fail-soft system		
REQ-12.04.07-TS-0306.0003	redundancy		
REQ-12.04.07-TS-0306.0004	Indication of failure		
REQ-12.04.07-TS-0306.0005	Design constraint		
REQ-12.04.07-TS-0306.0006	Validation of data		
REQ-12.04.07-TS-0306.0007	self-checking		
REQ-12.04.07-TS-0306.0008	Safety Case		
REQ-12.04.07-TS-0306.0009	Authentication for Management Access		
REQ-12.04.07-TS-0306.0010	Confidentiality for Management Access		
REQ-12.04.07-TS-0306.0011	Authentication for CWP		
REQ-12.04.07-TS-0306.0012	Radio Gateway White List		
REQ-12.04.07-TS-0306.0013	Monitoring Confidentiality		
REQ-12.04.07-TS-0306.0014	Monitoring Integrity		
REQ-12.04.07-TS-0306.0015	Monitoring Authentication		
	Maintainab	ility	
REQ-12.04.07-TS-0307.0001	Downtime for total OTW		
REQ-12.04.07-TS-0307.0002	downtime for a single OTW monitor		
REQ-12.04.07-TS-0307.0003	downtime for PTZ		
REQ-12.04.07-TS-0307.0004	downtime for communication between RTC and airport		
REQ-12.04.07-TS-0307.0005	downtime for total system and sub-system		
Reliability			
REQ-12.04.07-TS-0308.0001	maximum MTBF for total OTW		
REQ-12.04.07-TS-0308.0002	maximum MTBF for a single OTW		

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REQ-12.04.07-TS-0308.0003	maximum MTBF for PTZ		
REQ-12.04.07-TS-0308.0004	maximum MTBF for XXX		
REQ-12.04.07-TS-0308.0005			
REQ-12.04.07-TS-0308.0006			
REQ-12.04.07-TS-0308.0007			
REQ-12.04.07-TS-0308.0008	maximum delay for picture in OTW		
Design and construction constraints			
REQ-12.04.07-TS-0309.0001	Airport Constructions		
REQ-12.04.07-TS-0309.0002	Modular Design		
REQ-12.04.07-TS-0309.0003	Modular Design		
REQ-12.04.07-TS-0309.0004	QoS monitoring		
REQ-12.04.07-TS-0309.0005	Modular Design		
Functional block interface requirements			
REQ-12.04.07-TS-0310.0001	Interface Surveillance Sensors		
REQ-12.04.07-TS-0310.0002	Interface Surveillance Sensors		
REQ-12.04.07-TS-0310.0003	Interface Camera		
REQ-12.04.07-TS-0310.0004	Interface Radios		
REQ-12.04.07-TS-0310.0005	Interface Airport Systems		
REQ-12.04.07-TS-0310.0006	Interface		
REQ-12.04.07-TS-0310.0007	Interface Phone		
REQ-12.04.07-TS-0310.0008	Interface SWIM		
REQ-12.04.07-TS-0310.0009	Interface AFTN, FDP		
REQ-12.04.07-TS-0310.0010	Interface FDP or SWIM if available		
REQ-12.04.07-TS-0310.0011	EUROCAE Compliant		

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